

# **Instruction Manual for Evaluation Board of The TB6569FTG**

July 28, 2016

Rev.1.0

## 【Outline】

The TB6569FTG is a brushed DC motor driver corresponding to the constant current PWM control system and the direct PWM control system.

BiCD process is adopted. Ratings of 50V and 4.5A (@ Power supply voltage (VM)  $\leq$  36V) are realized. When the power supply voltage (VM) is more than 36V, please use the IC by configuring the current range of 4.0A or less.

This evaluation board mounts necessary components to evaluate the IC.

Brushed DC motor can be controlled by the direct PWM drive.

In case of controlling the brushed DC motor by the constant current PWM drive, please remove the short resistor ( $0\Omega$ ), which is mounted to R2. Then, replace the current detection resistor that is appropriate for the constant current PWM control.

Please sense controllability of a brushed DC motor by applying the TB6569FTG.

## 【Note】

In using, please be careful about the thermal condition sufficiently.

For each control signal, please refer to the IC specifications by accessing to the following URL:

<http://toshiba.semicon-storage.com/ap-en/product/linear/motordriver/detail.TB6569FTG.html>

Further, the application of this evaluation board is limited to the purpose of evaluating and learning the motor control. Please do not ship them to a market.

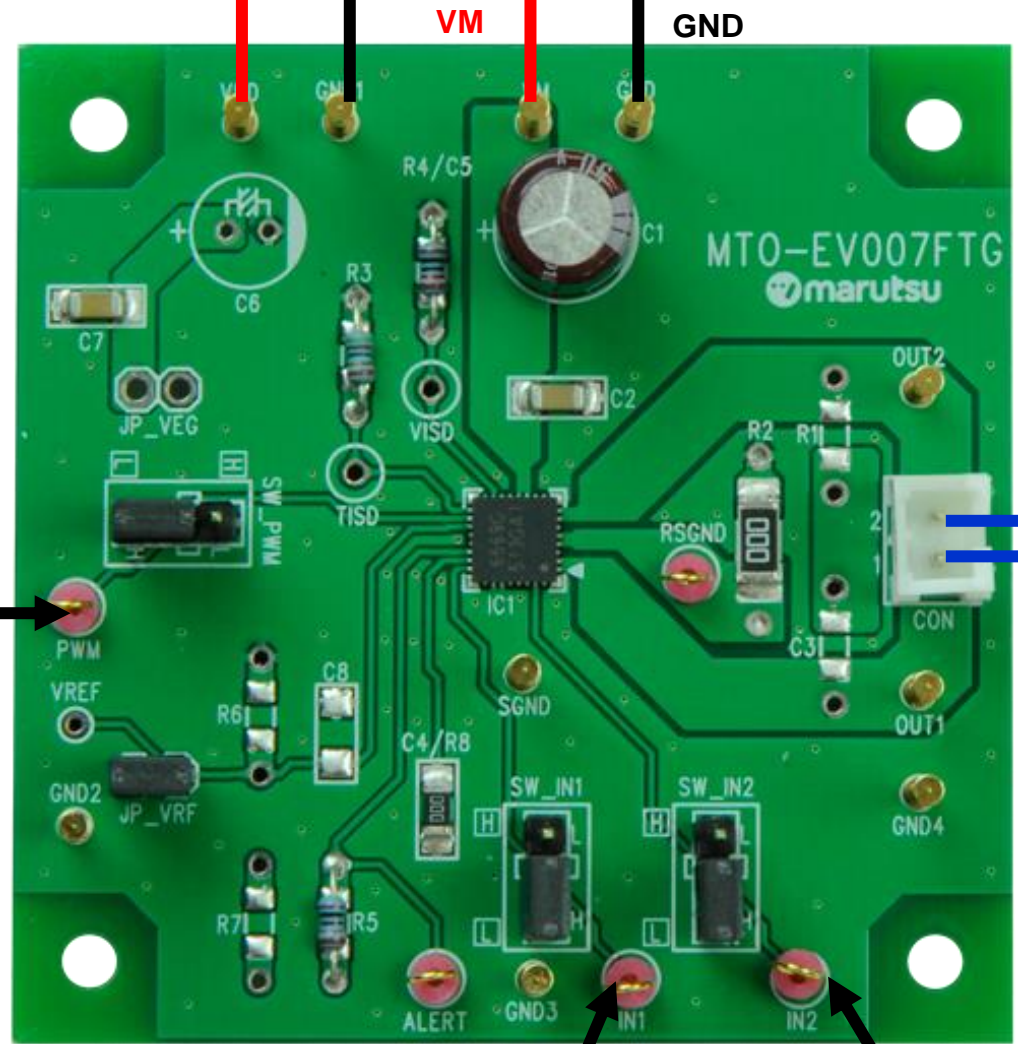
# Connection to Evaluation Board 1 【Direct PWM Control】



\*Supply the power in using the switch on the board.

Power supply for board: VDD (3.0V to 5.5V)

Power supply for motor: VM (10V to 47V)



Motor control signal input

Motor control signal input

Brushed DC motor

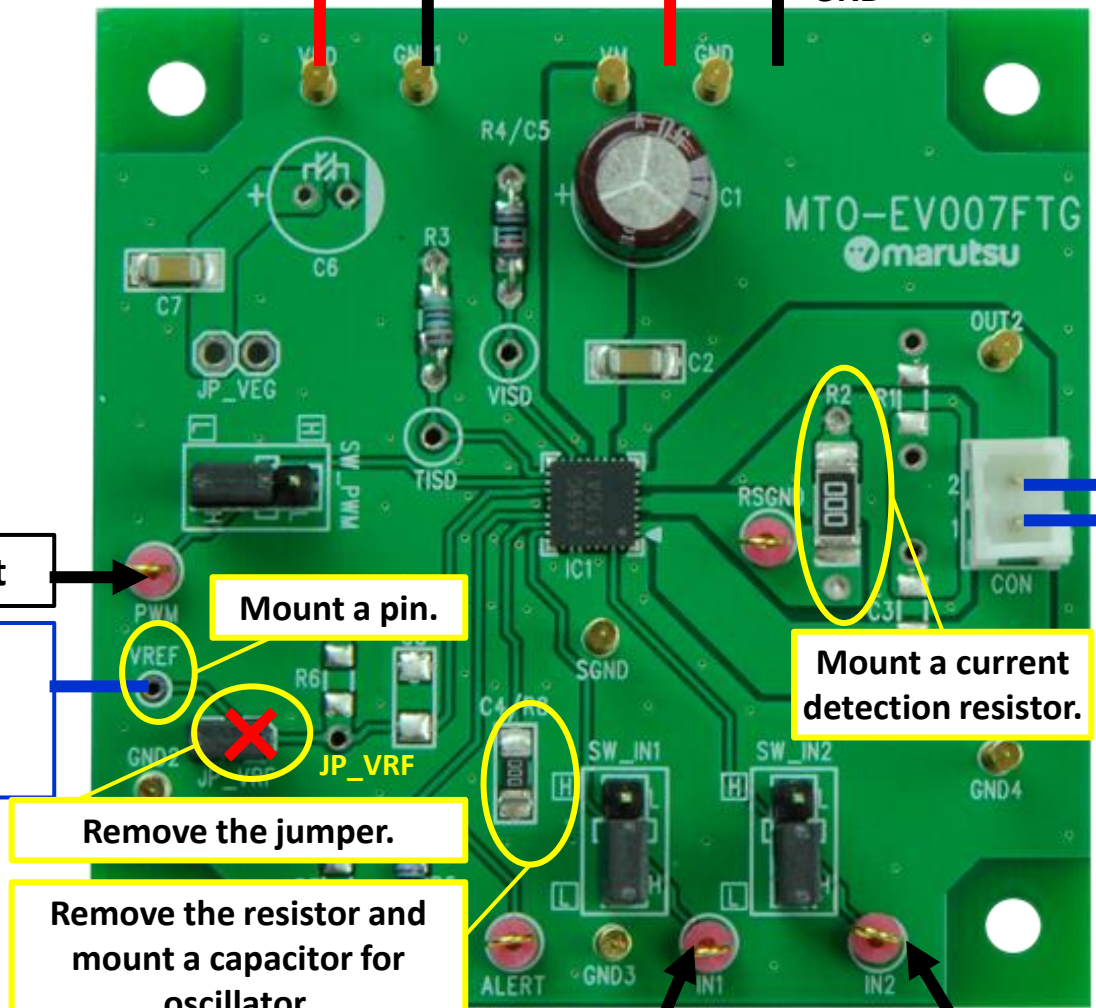
# Connection to Evaluation Board 2 【Constant Current PWM Control】



\*Supply the power in using the switch on the board.

Power supply for board: VDD (3.0V to 5.5V)

Power supply for motor: VM (10V to 47V)



Motor control signal input

Reference voltage for motor current set  $V_{ref}$  (0V to 3.6V)

Mount a pin.

Remove the jumper.

Remove the resistor and mount a capacitor for oscillator.

Mount a current detection resistor.

Brushed DC motor

Motor control signal input

# Setting Evaluation Board 1

## Setting motor current

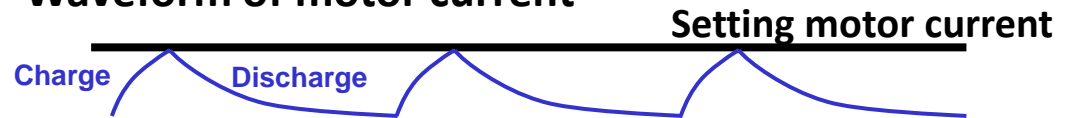
## Setting motor current

$$I_{out(max)} = V_{REF(gain)} \times \frac{V_{ref}(V)}{R_{RS}(\Omega)}$$

$V_{REF(gain)}$ : Decay ratio of  $V_{REF} = 1/10.0$  (typ.).

Current detection resistor should be remounted on the board because the resistor of  $R_{RS}$  ( $0\Omega$ ) is mounted.

## Waveform of motor current

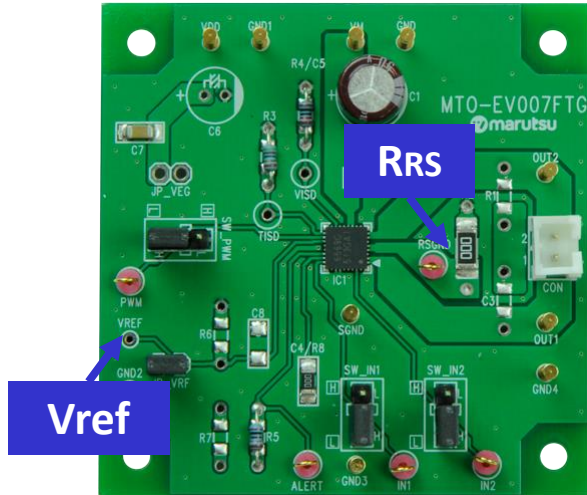
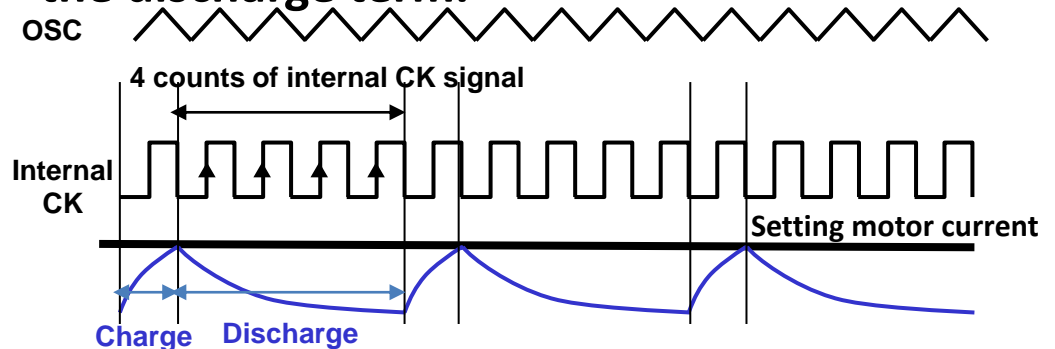


## Setting formula of OSC frequency

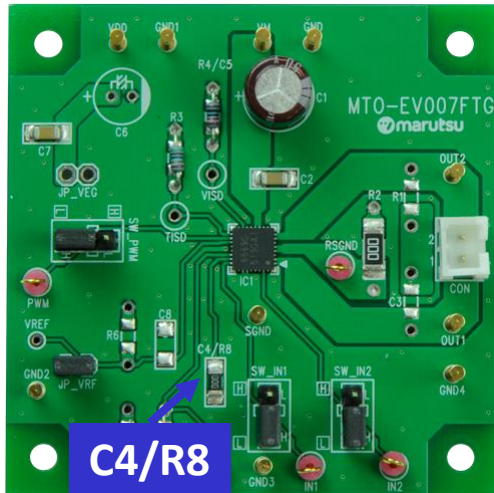
$$f_{OSC} = 0.42 / (C_{osc}[F] \times 10^3)$$

\* It is adjusted by the capacitor connected to C4/R8.

## Relation of the motor current waveform and the discharge term.



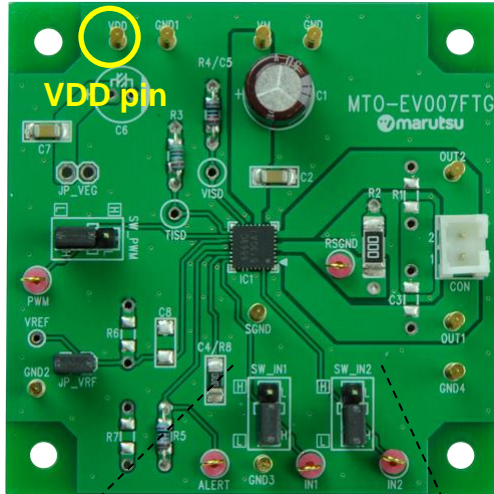
## Setting discharge term of constant current control



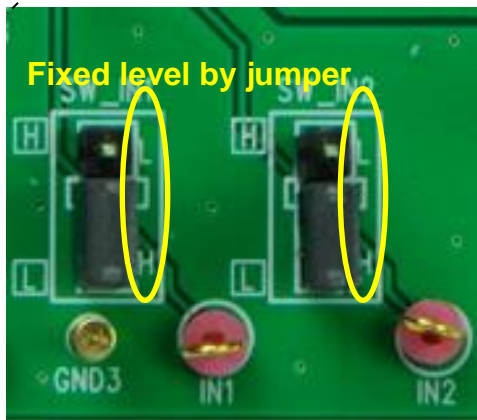


# Setting Evaluation Board 2

## Setting motor operation

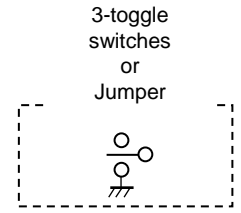
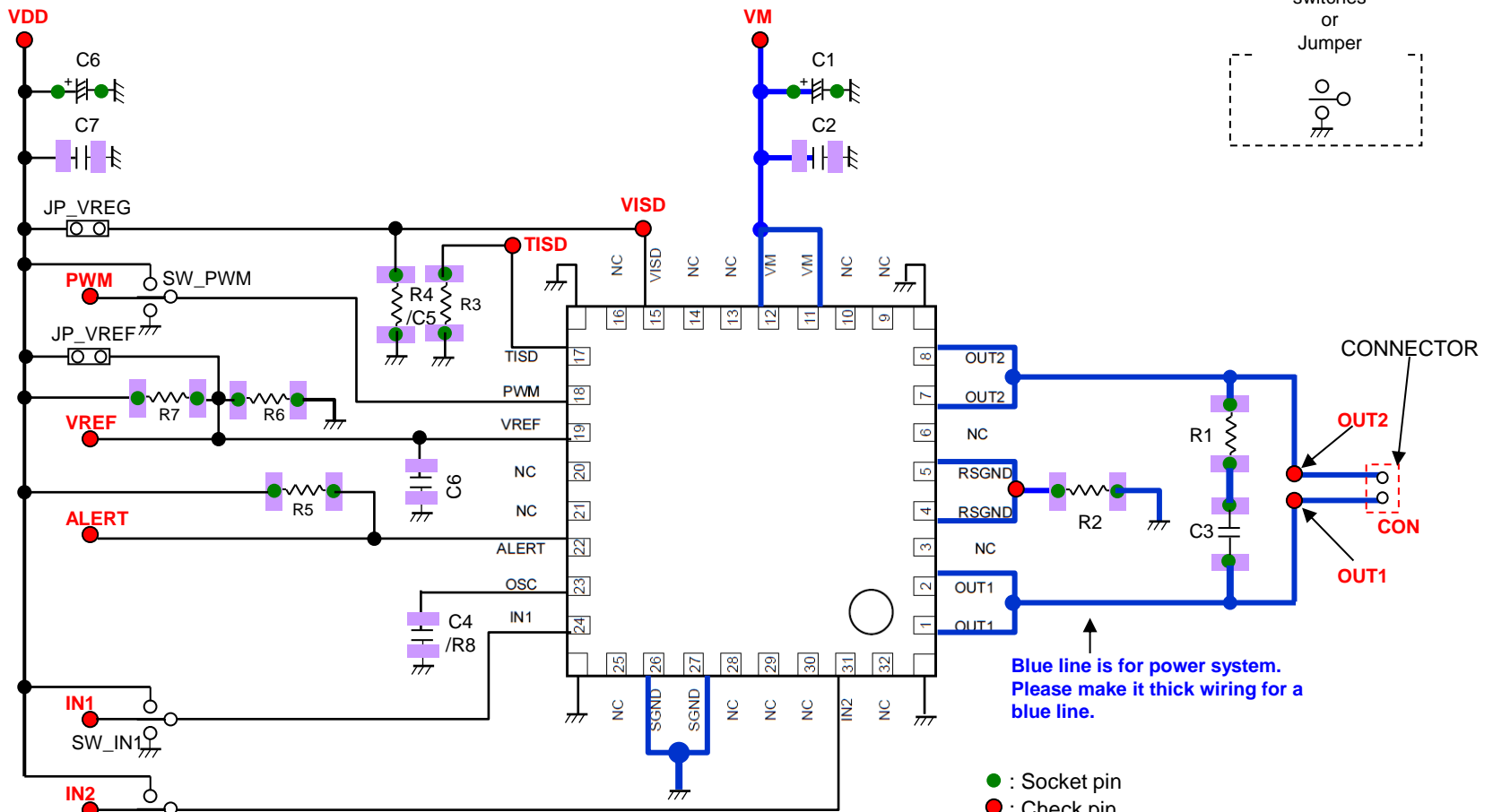


**【Enhanced figure of jumper part】**



Jumper indicated on the left is adopted on this evaluation board to set operation of the TB6569FTG. To select the function by the jumper, supply the voltage of high level by VDD pin. In the left figure, fixed level of the silk near the jumper is indicated inside the white frame. Please change the short position according to the configuration of the usage function. In case of inputting the signal externally, please remove the short pin.

# Circuit of Evaluation Board



Blue line is for power system.  
Please make it thick wiring for a blue line.

- : Socket pin
- : Check pin
- ⊞ : Jumper
- : Solder land + Through hole  
(Please provide the land for surface-mounting component which has a through hole.)
- : Solder land